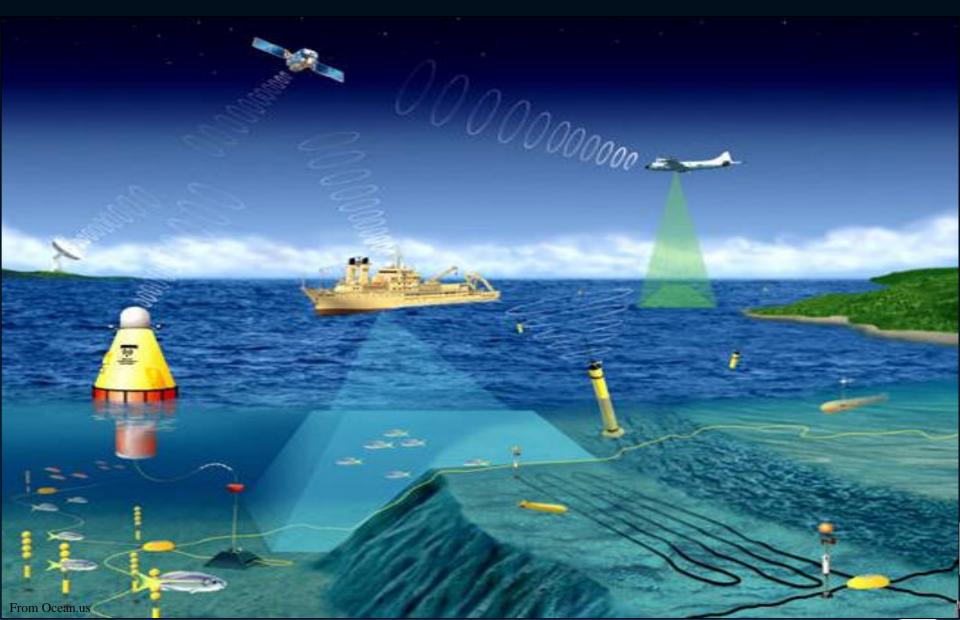
Using Ocean Observing Systems & Real Time Data to monitor and clean up Oil Spills





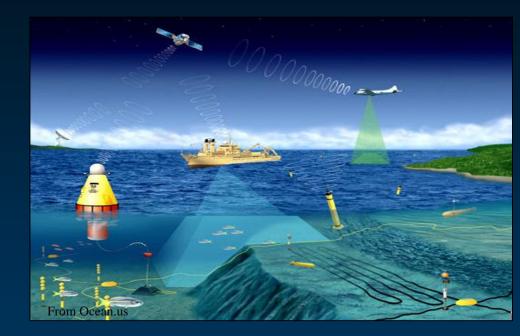
Ocean Observing Systems



Ocean Observing Systems

As a system, the components provide:

- 1. Continuous data sets
- High quality, accurate data through concurrent measurement by many components
- 3. Means of collecting data without immediate human presence
- Means of collected valuable data during dangerous conditions like storm events (see #3)

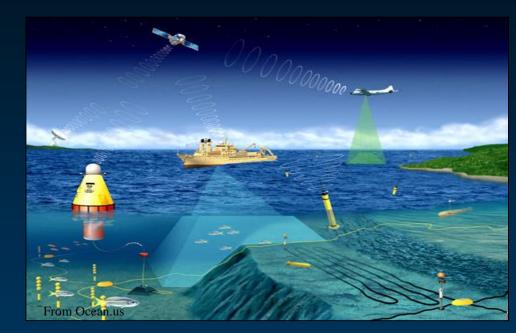




Ocean Observing Systems

Continuous data sets are important because they:

- 1. Show the entire big picture, not just small pieces of information here and there
- 2. Provide large amounts of quality data to input into forecast models



So not only do scientists use ocean observing system data to see where spilled oil is now, but also to forecast where it is going!

The Components



Remotely Operated Vehicles

Some of the first images we saw after the Deepwater Horizon incident were from Remotely Operated Vehicles, or ROVs

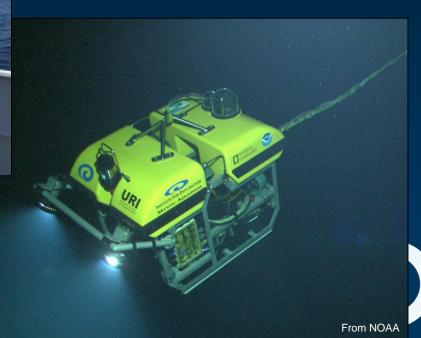


*Note the ROV's claw in the center of the picture

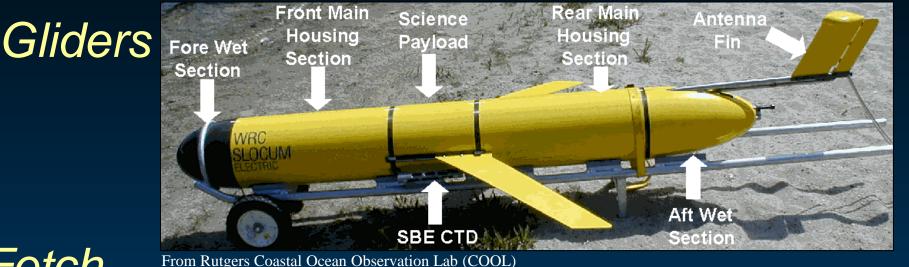


Remotely Operated Vehicles

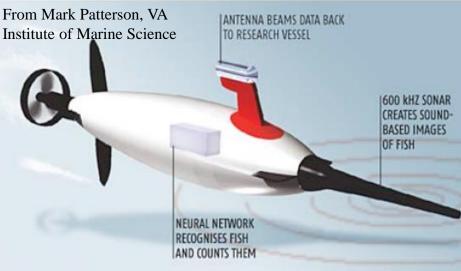




Autonomous Underwater Vehicles (AUVs)









REMUS

Buoys

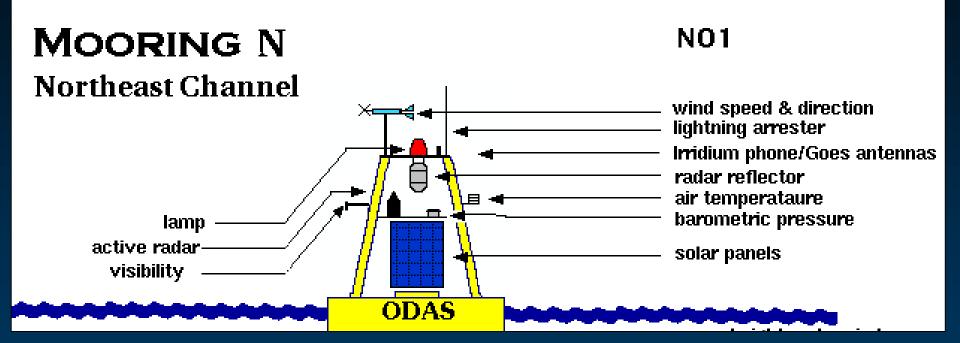


Equipped with sensors that can measure:

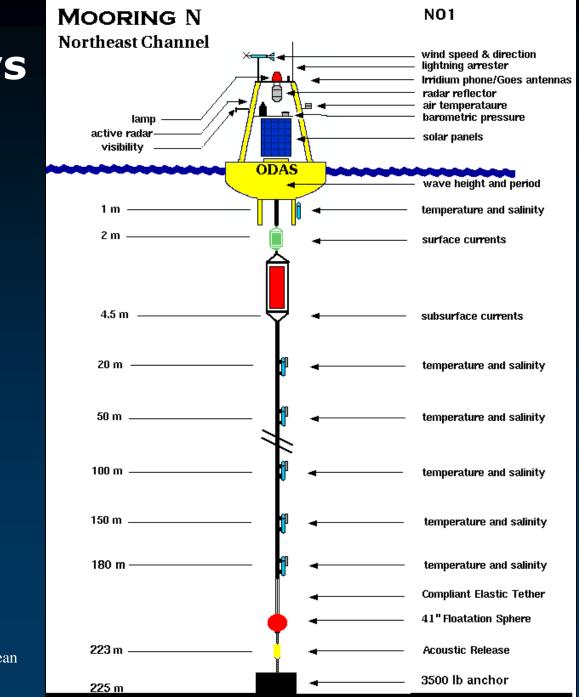
- Air & water temperature
- Wind speed & direction
- Water current speed & direction
- Wave height & period
- Atmospheric pressure
 ...and more



Buoys



From Gulf of Maine Ocean Observing System (GoMOOS)

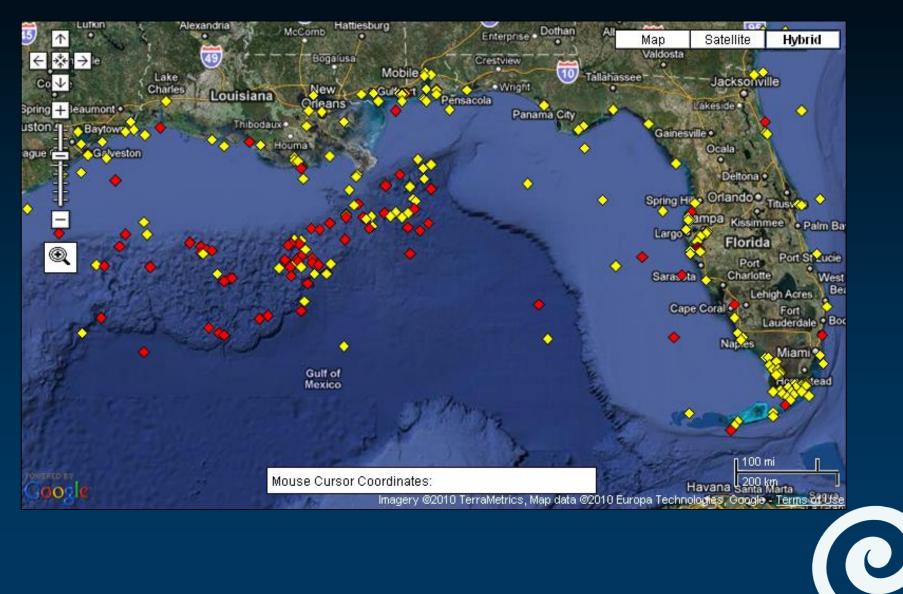


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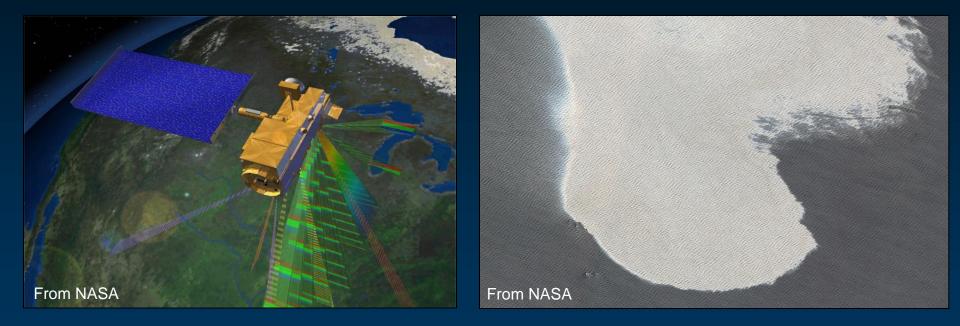
From Gulf of Maine Ocean Observing System (GoMOOS)

Buoys

Buoys



Satellite photos and data-images were, and will continue to be, integral in the monitoring and clean up of the Gulf oil spill



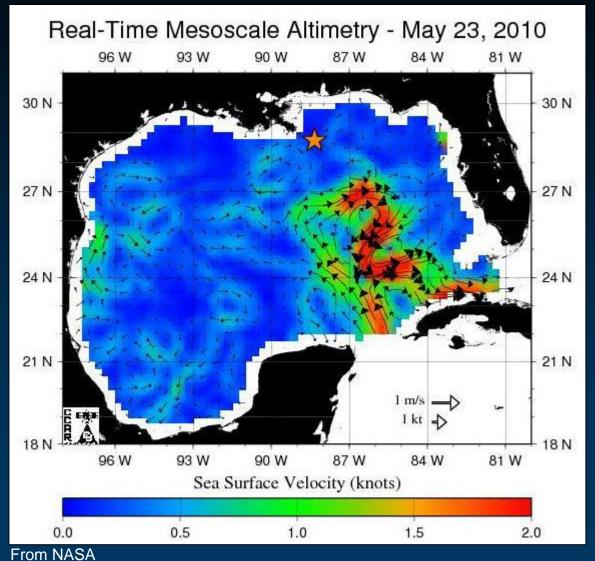
From National Geographic Taken on 4/21/2010. You can see the burning oil rig and smoke moving to the southeast.





Taken 4/25/10. Oil slick as seen from NASA satellite.





Satellite image of sea surface currents as measured using sea surface altimetry. The Loop Current can be seen in larger vectors and faster speeds.



High Frequency (HF) Radar

Antennas 25 and 13 MHz

Transmit

5 MHz

Receive Antenna

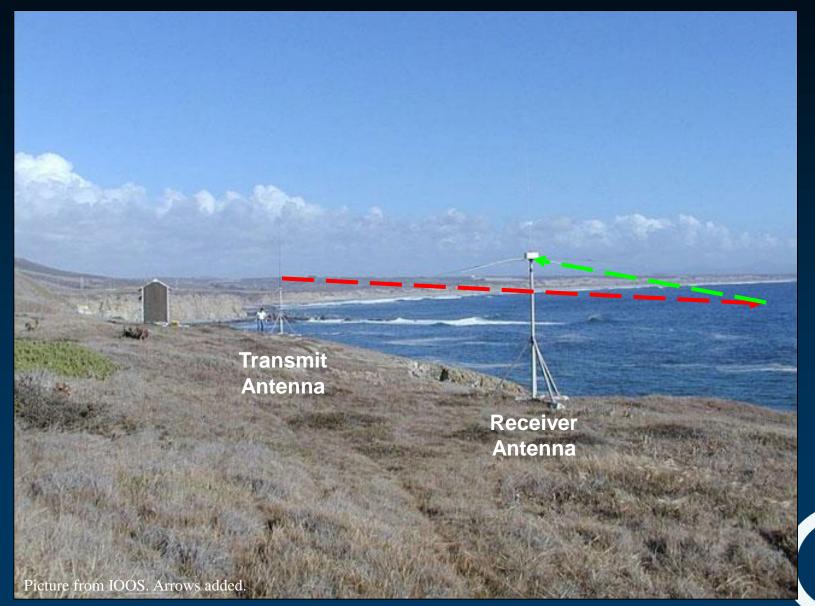
From J. Kohut; Rutgers Coastal Ocean Observation Lab (COOL)

 Originally designed to track submarines during WWII

 Now used to measure surface water currents' speed and direction

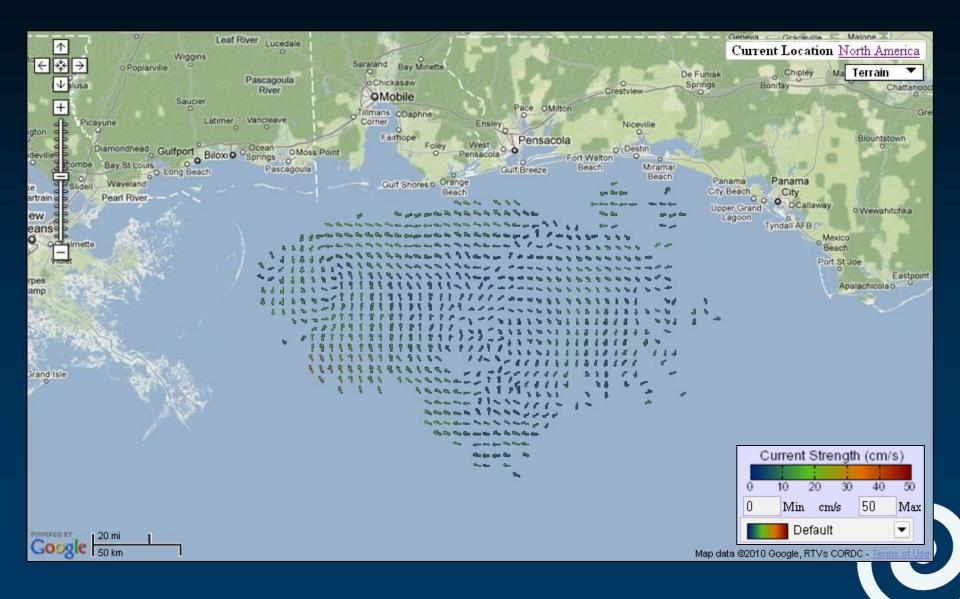


High Frequency (HF) Radar

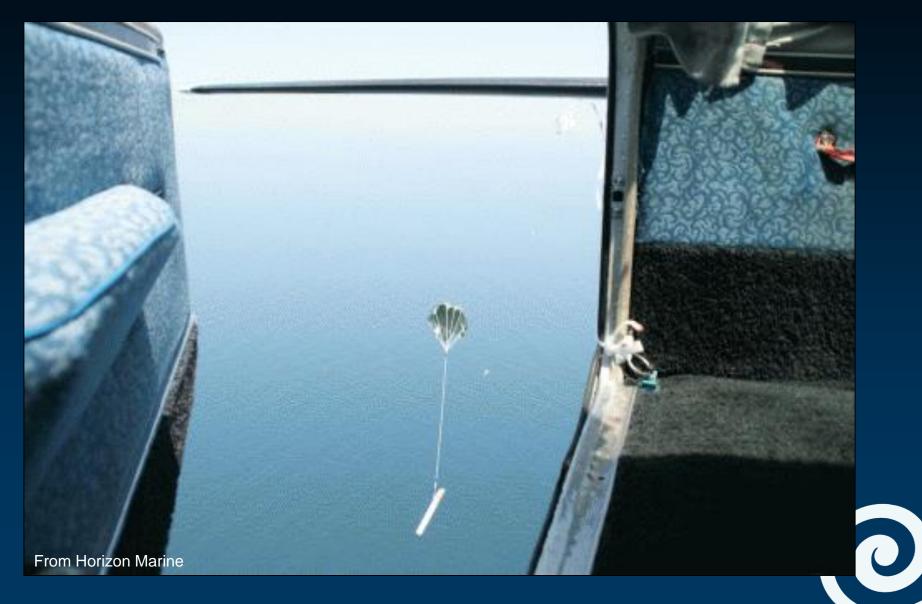


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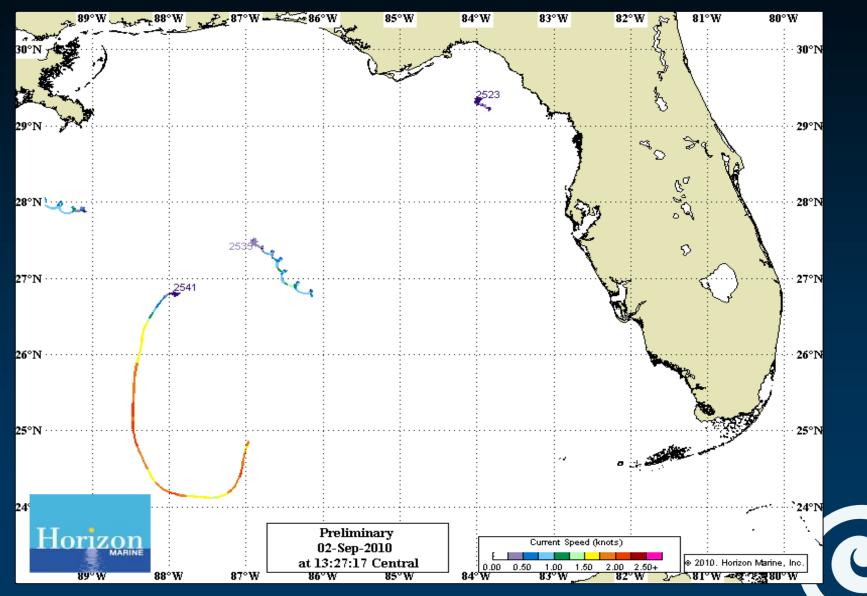
High Frequency (HF) Radar

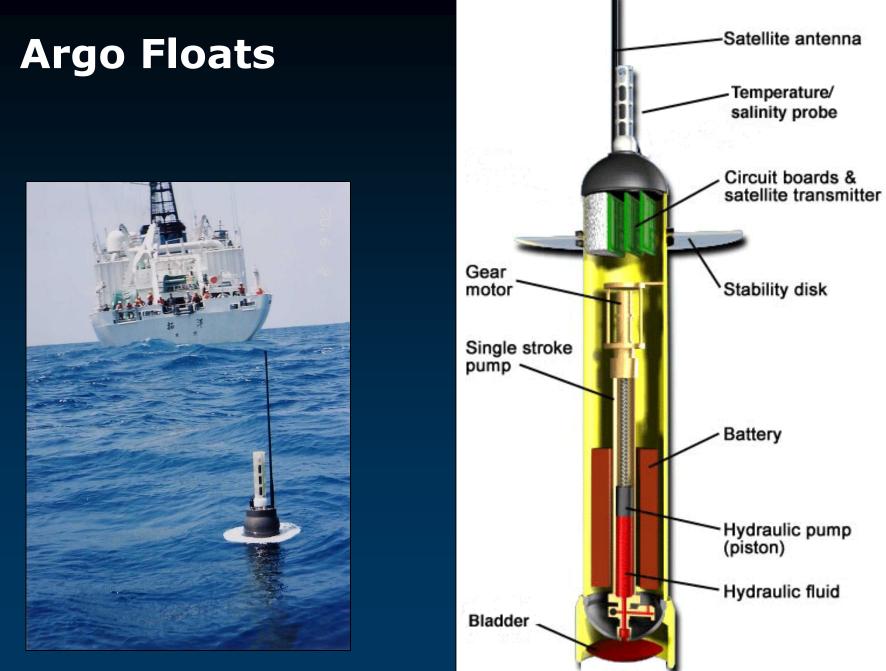


Air-deployed Drifting Buoys



Air-deployed Drifting Buoys





From Argo

8. Data sent to weather and climate forecasting centres around the world

1. Float deployed by ship or aircraft

6. Up to 12 hours at surface to transmit data to satellite

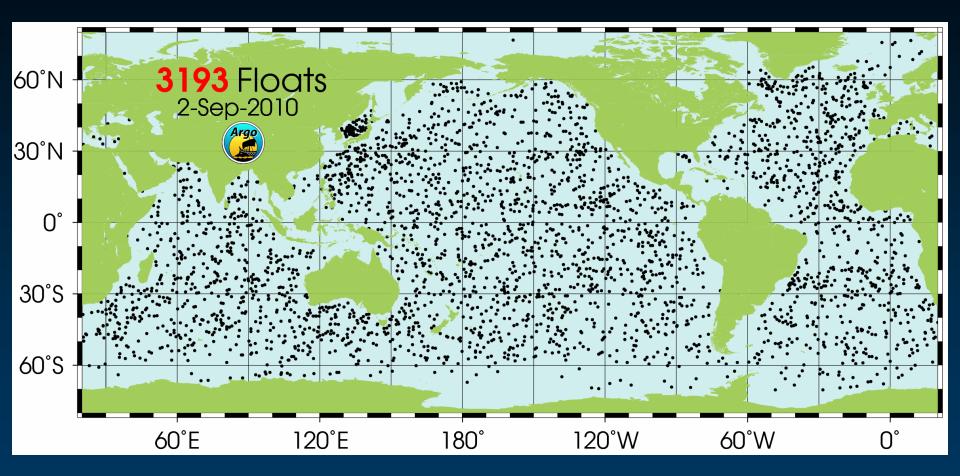
2. Slow descent to 2000 metres 6 hours at 10 cm/s 5. Temperature & salinity profile recorded during ascent 7. Oil pumped back to internal reservoir New cycle begins

3. Drift for 9 days with ocean currents

From Argo

4. Oil pumped from internal reservoir to inflate external bladder causing float to rise

Argo Floats

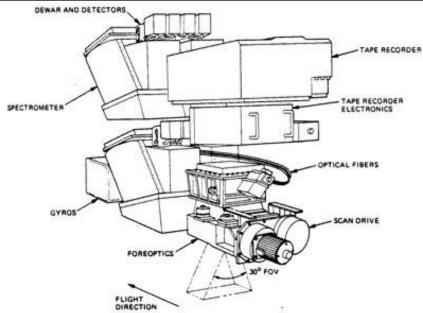




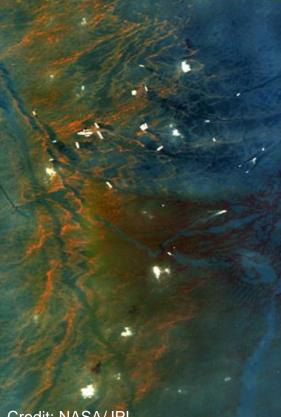
Aircraft-mounted sensors

NASA's Airborne Visible/Infrared Imaging Spectrometer (AVIRIS) is used to map the occurrence, amount, thickness and condition of surface oil in the Gulf of Mexico.





Top: NASA ER-2 aircraft, on which AVIRIS was mounted. Bottom: Labeled figure of AVIRIS. Right: AVIRIS map of Louisiana coast and surface oil.



Credit: NASA/JPL-Caltech/Dryden/USGS/UC Santa Barbara

On-site Research Vessels



NOAA R/V Henry B. Bigelow. From nola.com.



NOAA R/V Gordon Gunter. From NOAA.



NOAA R/V Pisces. Credit: NOAA.



NOAA R/V Nancy Foster. Credit: NOAA.